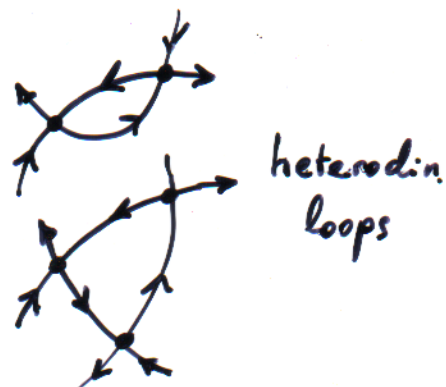
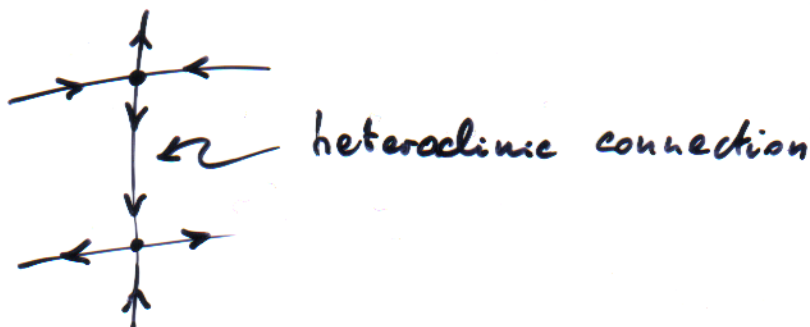
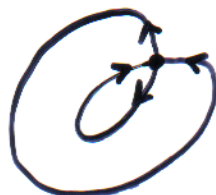


Homoclinic and heteroclinic connections

A trajectory connecting two saddles is called heteroclinic connection

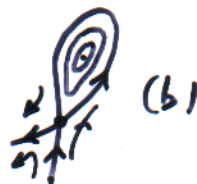


A trajectory connecting a saddle to itself is called homoclinic connection (or homoclinic orbit or homoclinic loop)



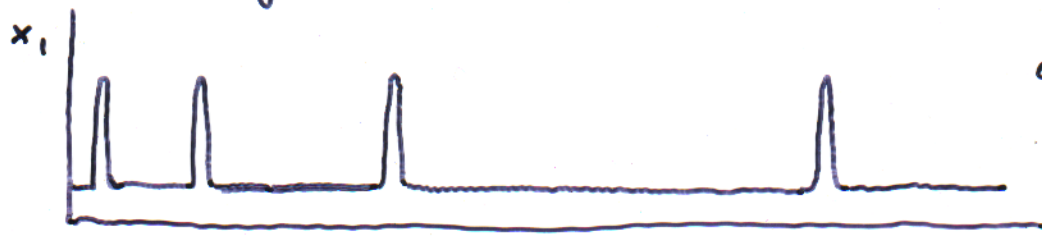
double homoclinic loop

homod. in \mathbb{R}^3



The region inside the homoclinic loop is an invariant set.

- (a) attracting homoclinic loop
- (b) neutral " "
- (c) repelling " "

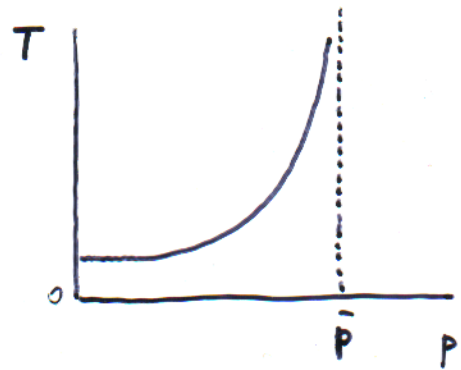
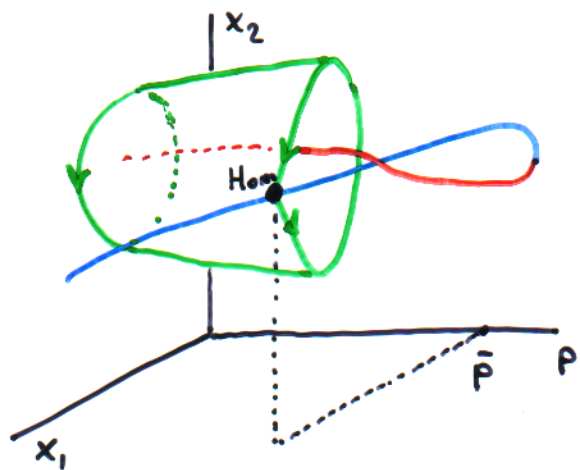
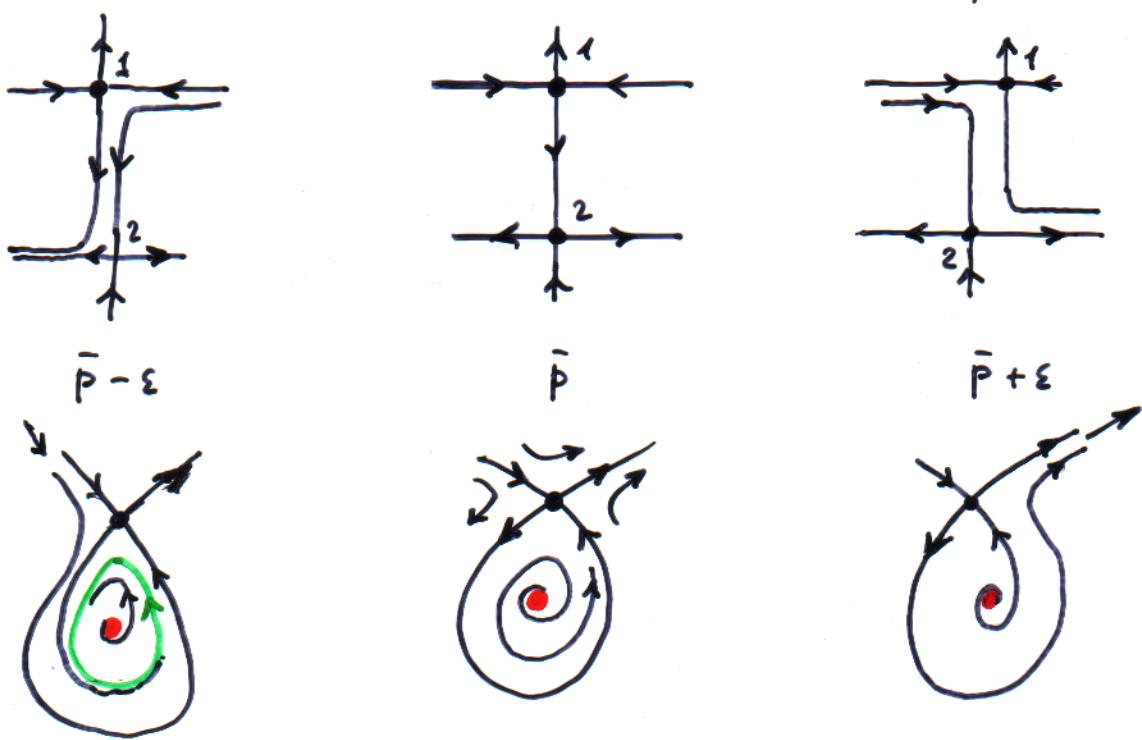


inside the loop in case (a)

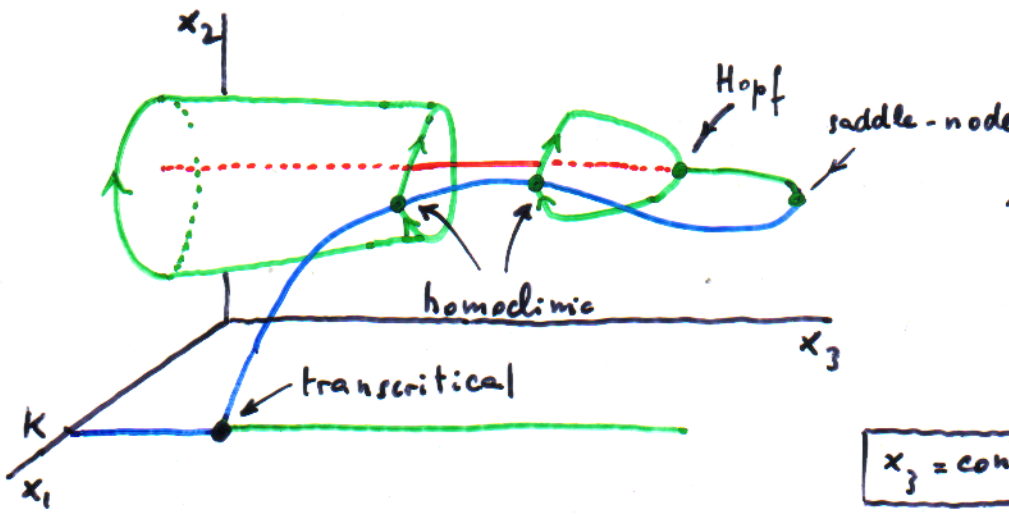
time

Heteroclinic and homoclinic bifurcations

In general, a system with an heteroclinic or homoclinic connections is structurally unstable.



Ex. 1 Tritrophic food chain



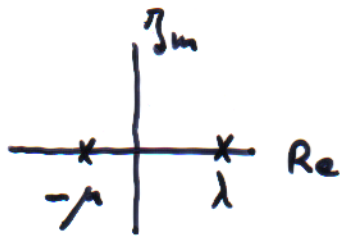
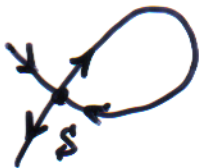
$$\dot{x}_1 = r x_1 \left(1 - \frac{x_1}{K}\right) - \frac{q x_1}{b+x_1} x_2$$

$$\dot{x}_2 = e \frac{a x_1}{b+x_1} x_2 - m x_2 - \frac{c x_2}{d+x_2} x_3$$

$x_3 = \text{const.}$

$$\frac{c x_2}{d+x_2} x_3$$

Andronov's theorem in \mathbb{R}^2



$$\sigma = \lambda - \mu$$

↑ saddle value

Close to the saddle : $e^{\lambda t}$ against $e^{-\mu t}$

$$\sigma < 0 \quad [\log \mu > \log \lambda]$$

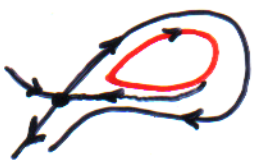
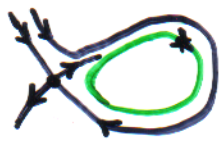
$$\sigma > 0 \quad [\log \mu < \log \lambda]$$

the homoclinic loop attracts

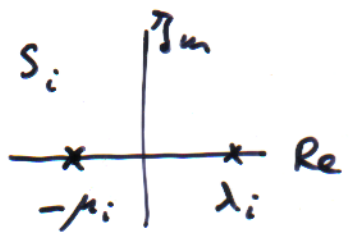
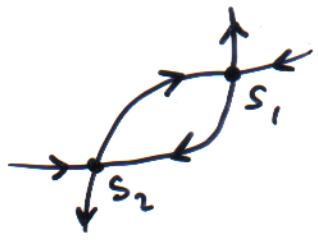
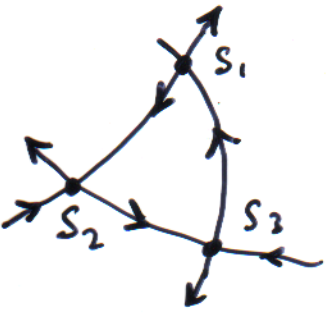
the homoclinic loop is repelling

the cycle obtained through perturbation is stable

the cycle obtained through perturbation is unstable



Extension to heteroclinic loops [Reyn 1979]



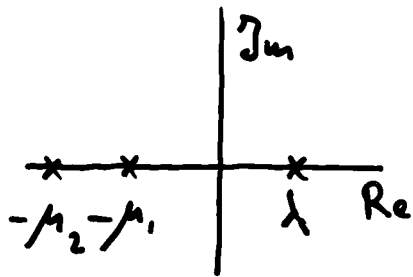
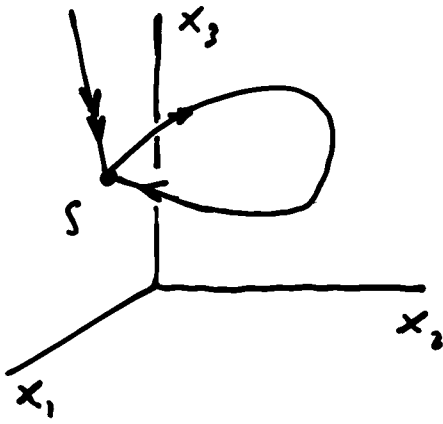
If a parameter is perturbed the loop breaks and a cycle appears (if the perturbation has the right sign)

Moreover

$$\sum \log \mu_i > \sum \log \lambda_i \Rightarrow \text{stable cycle}$$

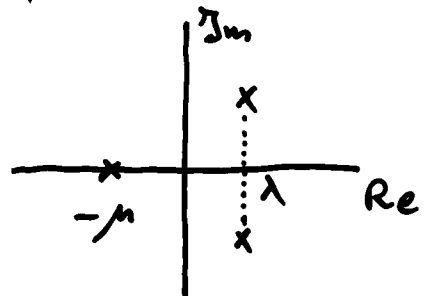
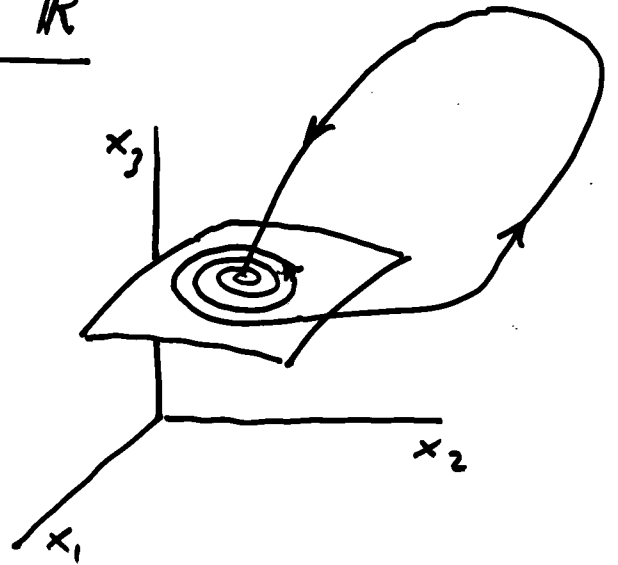
$$\sum \log \mu_i < \sum \log \lambda_i \Rightarrow \text{unstable cycle}$$

Shilnikov's Theorem in \mathbb{R}^3



real saddle

$$\sigma = \lambda - \mu_1$$



complex saddle

$$\sigma = \lambda - \mu$$

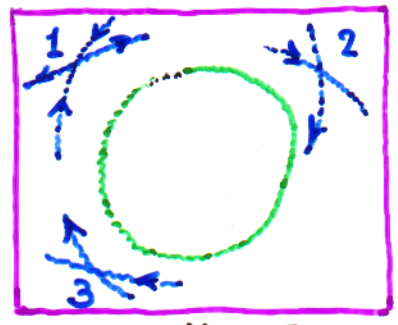
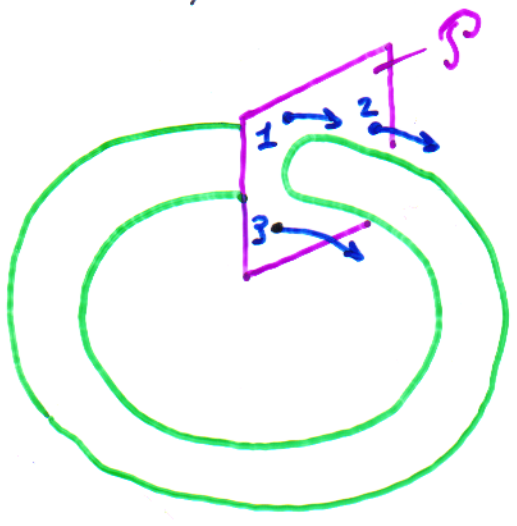
eigenvalue closest to imaginary axis

{	real	positive ($\sigma < 0$)	\Rightarrow stable cycle	}	
		negative ($\sigma > 0$)	\Rightarrow unstable cycle		
	complex	positive real part	$\Rightarrow \infty$ cycles		} "chaos"
		negative real part	$\Rightarrow \infty$ cycles		

- The theorem holds provided the saddle is not degenerate (11 conditions! Champneys-Kuznetsov 1994)
- The theorem has been extended to \mathbb{R}^n .

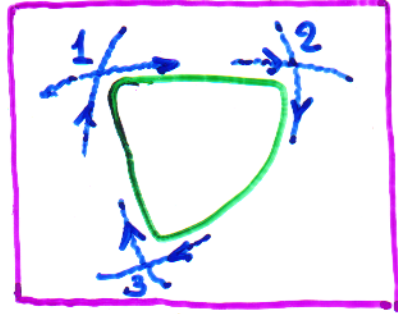
Torus destruction

Torus destruction is a second route to chaos. It is characterized by a single (but global) bifurcation, namely an heteroclinic bifurcation.



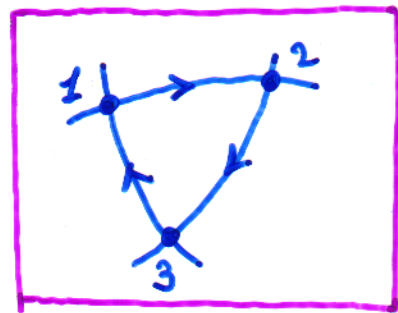
torus and period 3 cycle

↓ $p + \delta p$



pinched torus

↓ $p + \delta p$



collision:
heteroclinic loop

↓ $p + \delta p$
(CHAOS)

