

Quasi periodicity

$$y(t) = A \sin \omega_1 t + B \sin \omega_2 t$$

$$\frac{\omega_1}{\omega_2} = \begin{cases} \text{rational} = \frac{p}{q} & (\text{probability} = 0) \\ \text{irrational} & (\text{probability} = 1) \end{cases}$$

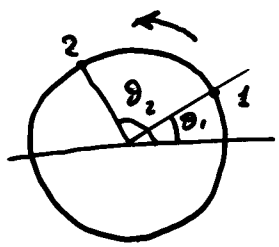
$$\frac{\omega_1}{\omega_2} = \frac{p}{q} = \frac{T_2}{T_1} \Rightarrow p T_1 = q T_2 \Rightarrow y(\cdot) \text{ is periodic of period } T$$

$$T = p T_1 = q T_2$$

$\omega_i = \frac{2\pi}{T_i}$

$$\frac{\omega_1}{\omega_2} = \text{irrational} \Rightarrow y(\cdot) \text{ is } \underline{\text{quasi periodic}}$$

Ex. 1. Two runners



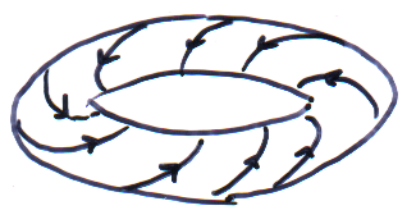
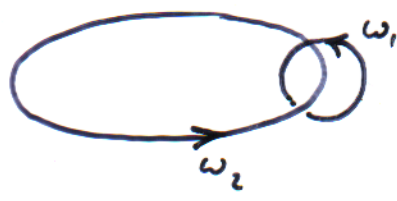
$$\dot{\theta}_1 = \omega_1$$

$$\dot{\theta}_2 = \omega_2$$

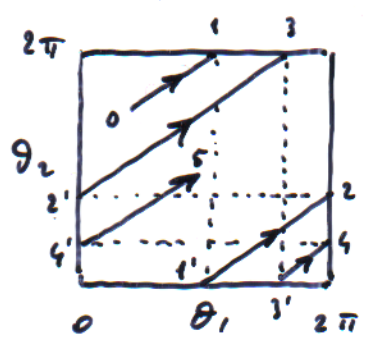
If $\frac{\omega_1}{\omega_2} = \frac{p}{q}$ runner 1 will complete p tours when runner 2 will complete q tours

Thus, after a period $T = p \frac{2\pi}{\omega_1} (= q \frac{2\pi}{\omega_2})$ the two runners will be in the same conditions.

Visualization on torus



2-torus



$$\frac{d\theta_2}{d\theta_1} = \frac{\dot{\theta}_2}{\dot{\theta}_1} = \frac{\omega_2}{\omega_1}$$

If $\frac{\omega_1}{\omega_2} = \frac{p}{q}$ we have a cycle on torus -

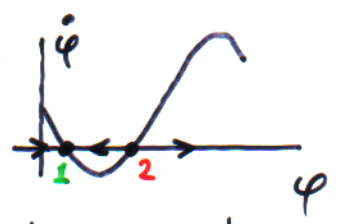
If $\frac{\omega_1}{\omega_2}$ is irrational we have a trajectory on torus that never comes back to the initial conditions but densely covers the entire torus.

Ex. 2 Two friends running (phase locking)

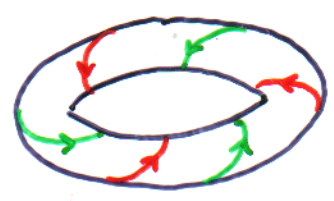
$$\begin{cases} \dot{\theta}_1 = \omega_1 + k_1 \sin(\theta_2 - \theta_1) \\ \dot{\theta}_2 = \omega_2 + k_2 \sin(\theta_1 - \theta_2) \end{cases} \quad \varphi = \theta_1 - \theta_2$$

$$\dot{\varphi} = \dot{\theta}_1 - \dot{\theta}_2 = \omega_1 - \omega_2 - (k_1 + k_2) \sin \varphi$$

$$\dot{\varphi} = 0 \iff \sin \bar{\varphi} = \frac{\omega_1 - \omega_2}{k_1 + k_2}$$



$$|\omega_1 - \omega_2| < k_1 + k_2$$

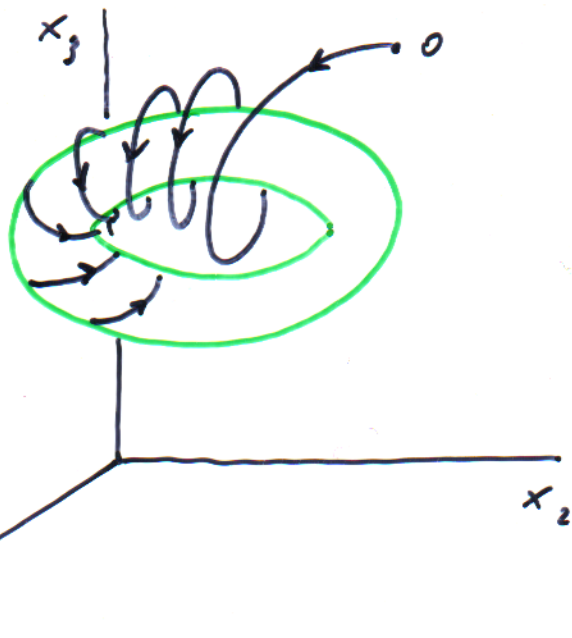


$$\omega^* = \lambda \omega_1 + (1 - \lambda) \omega_2$$

$$\lambda = \frac{k_2}{k_1 + k_2}$$

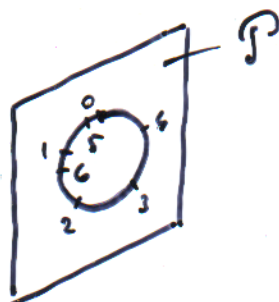
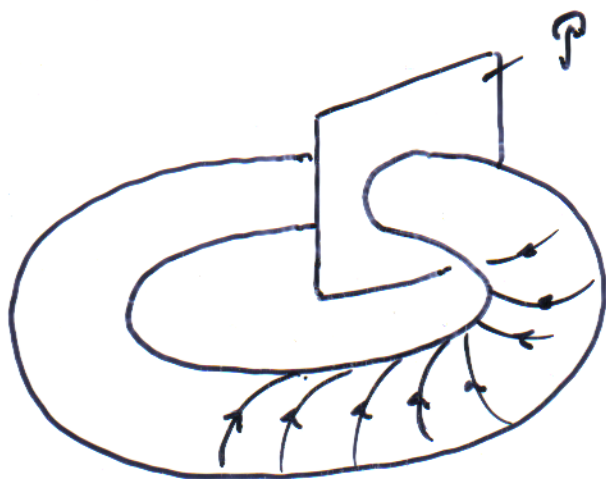
(If $|\omega_1 - \omega_2| > k_1 + k_2$ the behaviour is quasiperiodic)

Third order systems



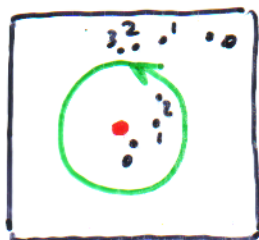
The trajectory starting from 0 tends toward the torus.

If the same happens for all points 0 close to the torus (also inside it) we say that the torus is an attractor

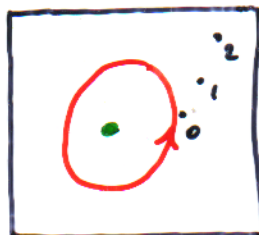


Poincaré section

Inside the torus there is a limit cycle



stable torus



unstable torus

In higher order systems we can also have saddle tori.

Non existence of tori

Theorem 1 (non existence condition)

If the divergence $\frac{\partial f_1}{\partial x_1} + \frac{\partial f_2}{\partial x_2} + \dots + \frac{\partial f_n}{\partial x_n}$ does not change sign in a domain $\Omega \subset \mathbb{R}^n$ (and, at most, annihilates on a manifold of dimension $n-1$) then there are no tori in Ω .

Proof Same arguments, used in Theorem 4 of lecture 6.

Ex. 3 (Lorenz system)

$$\dot{x}_1 = \sigma(x_2 - x_1)$$

$$\dot{x}_2 = r x_1 - x_2 - x_1 x_3$$

$$\dot{x}_3 = x_1 x_2 - b x_3$$

$$\text{divergence} = \frac{\partial f_1}{\partial x_1} + \frac{\partial f_2}{\partial x_2} + \frac{\partial f_3}{\partial x_3} = -\sigma - 1 - b < 0$$

Thus, in the Lorenz system trajectories converge (because volumes contract) so that there cannot be an attracting or repelling torus (because inside the torus there should be a repelling or attracting cycle).

Problems

(2)

P. 1. Reconsider the system (see Ex. 2)

$$\dot{\theta}_1 = \omega_1 + k_1 \sin(\theta_2 - \theta_1)$$

$$\dot{\theta}_2 = \omega_2 + k_2 \sin(\theta_1 - \theta_2)$$

Find a "conserved quantity" for this system (i.e. a sort of energy function V such that $V = \text{const.}$, i.e. $\dot{V} = 0$).

(3)

P. 2 - Consider the equations

$$m \ddot{\rho} = \frac{h^2}{m \rho^3} - k$$

$$\dot{\theta} = \frac{h}{m \rho^2}$$

$$h = \text{const.} > 0$$

These equations describe (in polar coordinates) the motion of a mass m subject to a central force of constant strength $k > 0$.

(i) Show that the system has a solution

$$\rho = R \quad \dot{\theta} = \omega$$

corresponding to uniform circular motion.

(ii) Find the frequency ω_r of small radial oscillations about the circular orbit

(iii) Show by a geometric argument that the motion is either periodic or quasiperiodic.