# Ex1: Two runners

$$\hat{\beta}_{1} = \hat{\beta}_{1} (1 - \hat{\beta}_{1}^{2}) , \quad \hat{\beta}_{2} = \hat{\beta}_{2} (1 - \hat{\beta}_{2}^{2}) , \quad x_{1} = \hat{\beta}_{1} \cos \theta_{1} , \quad x_{2} = \hat{\beta}_{1} \sin \theta_{1}$$

$$\hat{\theta}_{1} = \hat{\theta}_{1} (1 - \hat{\beta}_{1}^{2}) , \quad x_{1} = \hat{\beta}_{1} \cos \theta_{1} , \quad x_{2} = \hat{\beta}_{1} \sin \theta_{1}$$

$$\hat{\theta}_{2} = \hat{\theta}_{2} (1 - \hat{\beta}_{2}^{2}) , \quad x_{3} = \hat{\beta}_{2} \cos \theta_{2} , \quad x_{4} = \hat{\beta}_{2} \sin \theta_{2}$$

$$\hat{x}_{1} = \hat{x}_{1} - \hat{\omega}_{1} \times \hat{z}_{2} - (\hat{x}_{1}^{2} + \hat{x}_{2}^{2}) \times \hat{z}_{1}$$

$$\hat{x}_{2} = \hat{\omega}_{1} \times \hat{z}_{1} - (\hat{x}_{1}^{2} + \hat{x}_{2}^{2}) \times \hat{z}_{2}$$

$$\hat{x}_{3} = \hat{x}_{3} - \hat{\omega}_{2} \times \hat{z}_{4} - (\hat{x}_{2}^{2} + \hat{x}_{4}^{2}) \times \hat{z}_{3}$$

$$\hat{x}_{4} = \hat{\omega}_{2} \times \hat{z}_{3} + \hat{x}_{4} - (\hat{x}_{2}^{2} + \hat{x}_{4}^{2}) \times \hat{z}_{4}$$

$$\hat{y} \times \hat{z}_{1} = \hat{\beta}_{1} \cos \theta_{1} , \quad x_{2} = \hat{\beta}_{1} \sin \theta_{2}$$

$$\hat{z}_{3} = \hat{z}_{1} \cos \theta_{2} , \quad x_{4} = \hat{z}_{2} \sin \theta_{2}$$

$$\hat{z}_{4} = \hat{z}_{1} \cos \theta_{1} , \quad x_{2} = \hat{z}_{1} \sin \theta_{2}$$

$$\hat{z}_{3} = \hat{z}_{3} - \hat{z}_{1} \cos \theta_{2} , \quad x_{4} = \hat{z}_{2} \sin \theta_{2}$$

$$\hat{z}_{4} = \hat{z}_{1} \cos \theta_{1} , \quad x_{2} = \hat{z}_{1} \sin \theta_{2}$$

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$$\hat{z}_{5} = \hat{z}_{1} \cos \theta_{2} , \quad x_{5} = \hat{z}_{2} \cos \theta_{2} , \quad x_{5} = \hat{z}_{2} \sin \theta_{2}$$

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$$\hat{z}_{5} = \hat{z}_{5} \cos \theta_{2} , \quad z_{5} = \hat{z}_{5} \cos \theta_{2} , \quad z_{5} = \hat{z}_{5} \cos \theta_{2}$$

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$$\hat{z}_{7} = \hat{z}_{7} \cos \theta_{2} , \quad z_{7} = \hat{z}_{7} \cos \theta_{2}$$

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$$\hat{z}_{7}$$

 $y = A \times_2 + B \times_4$ 

### Notes:

- The invariant torus is the 2-dimensional manifold (x1+x2=1, x3+x4=1)
- W/w 2 rational  $\Rightarrow$  there are infinitely many stable (but not asymptotically stable) cycles on the torus. Fixing e-g-  $\times 10$  = 1,  $\times 20$  = 0, two different initial conditions with  $\times 30$  +  $\times 40$  = 1 belong to two different cycles.
- W/wz irrational => the dynamics on the torus is quasiperiodic. Each trajectory on the torus is aperiodic and densely full the torus. Trajectories starting from close initial conditions remain close for all t>0.
- The torus is K-dimensional, K>2, if there are K incommensurable frequencies (fi/fj irrational for any i ≠ j, i, j=1,..., K) in the system.

# Ex 2: Two friends running

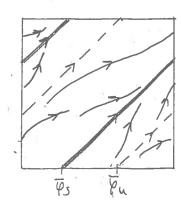
sindz cos dy - sm Q1 cos Q2

$$\dot{x}_{1} = \beta_{1} \cos \mathcal{Q}_{1} - \beta_{1} \sin \mathcal{Q}_{1} \dot{\mathcal{Q}}_{1} = \beta_{1} (1 - \beta_{1}^{2}) \cos \mathcal{Q}_{1} - \beta_{1} \sin \mathcal{Q}_{1} (\omega_{1} + K_{1} \sin \mathcal{Q}_{2} - \mathcal{Q}_{1}))$$

$$= x_{1} - \omega_{1} x_{2} - (x_{1}^{2} + x_{2}^{2}) x_{1} - \frac{K_{1} x_{2}}{\sqrt{x_{1}^{2} + x_{2}^{2}} \sqrt{x_{3}^{2} + x_{4}^{2}}} (x_{4} x_{1} - x_{2} x_{3})$$

#### Notes:

- ► Similarly for x2, x3, x4
- Nu-Wzl < K1+K2 ⇒ there are two cycles on the torus (one aymp. stable, the other unstable). The phase difference on the stable cycle is constant (phase locking)



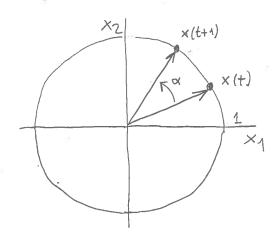
# Quasiperiodiaty in discrete time

$$y(t) = A sin(at)$$

$$\alpha/_{\Pi} = \frac{\rho}{q} \Rightarrow 2q\alpha = \rho 2\Pi \Rightarrow \gamma \text{ is periodic with period } T = 2q$$

of irrational > y is quasi periodic

EX: Rotation



$$x(t+1) = R \times (t)$$
 (linear system)

+ h.o.t. to make the unit circle an attractive invariant curve\*

$$x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
  $y(t) = A \times_2(t)$ 

Notes:

- by analogy with the continuous-time case. It is an invariant curve.
- ► 0/1 rational > there are infinitely many stable (not asymp. stable) cycles. E.g. two different initial conditions on the unit circle belong to to two different cycles.
- (same comments as in continuous true).
- The torus is K-dimensional,  $K\gg 1$ , if there are K rotation angles in commensurable with TT and among them  $(\alpha i/\pi, \lambda i/\alpha j)$  irrationals for all  $i\neq j$ , i,j=1,...,K

$$p(t+1) = p(t) + \frac{1-p(t)}{2} = \frac{1+p(t)}{2} \Rightarrow \bar{p} = 1$$
 is slobally stable

$$O(t+1) = O(t) + \infty$$

$$\begin{aligned} x_1(t+1) &= \beta(t+1)\cos\theta(t+1) = \frac{1}{2}(1+\beta(t))(\cos\theta(t))\cos\alpha - \sin\theta(t)\sin\alpha \\ &= \frac{1}{2}(x_1(t)\cos\alpha - x_2(t)\sin\alpha) + \frac{1}{2\sqrt{x_2^2(t)} + x_2^2(t)}(x_1(t)\cos\alpha - x_2(t)\sin\alpha) \end{aligned}$$

$$x_2(t+1) = --- = \frac{1}{2}(x_1(t) \sin \alpha + x_2(t) \cos \alpha) \left(1 + \frac{1}{\sqrt{x_1^2(t) + x_2^2(t)}}\right)$$

## A 2D torus in a 3D system

The Lorenz 1984 system: A low-order model of atmospheric circulation [1]

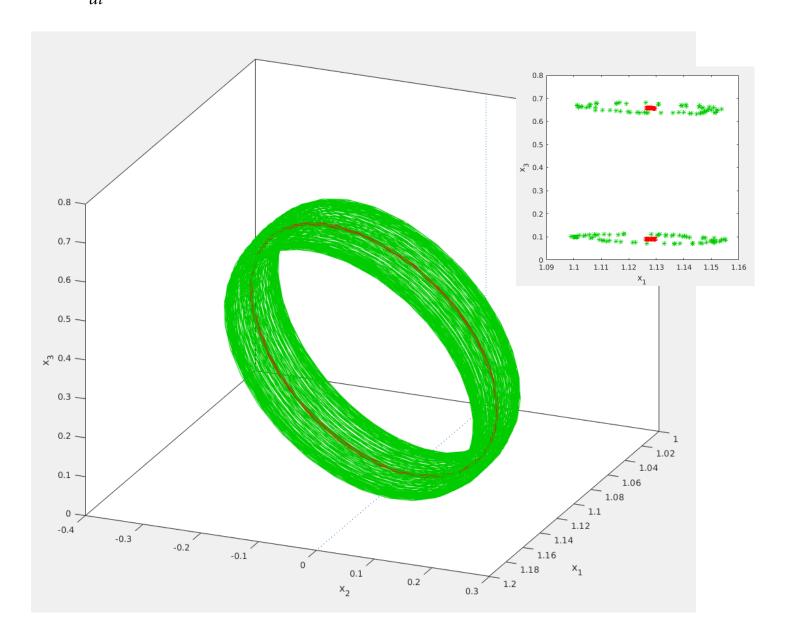
$$\frac{dx}{dt} = -y^2 - z^2 - ax + aF,$$

$$\frac{dy}{dt} = xy - bxz - y + G,$$

$$\frac{dz}{dt} = bxy + xz - z,$$

where x represents the strength of the globally averaged westerly current and y and z and are the strength of the cosine and sine phases of a chain of superposed waves.

Parameters: a = 0.25, b = 4, F = 2, G = 1.67



[1] E. N. Lorenz, Irregularity: a fundamental property of the atmosphere, *Tellus A*, 36, 98–110, 1984.