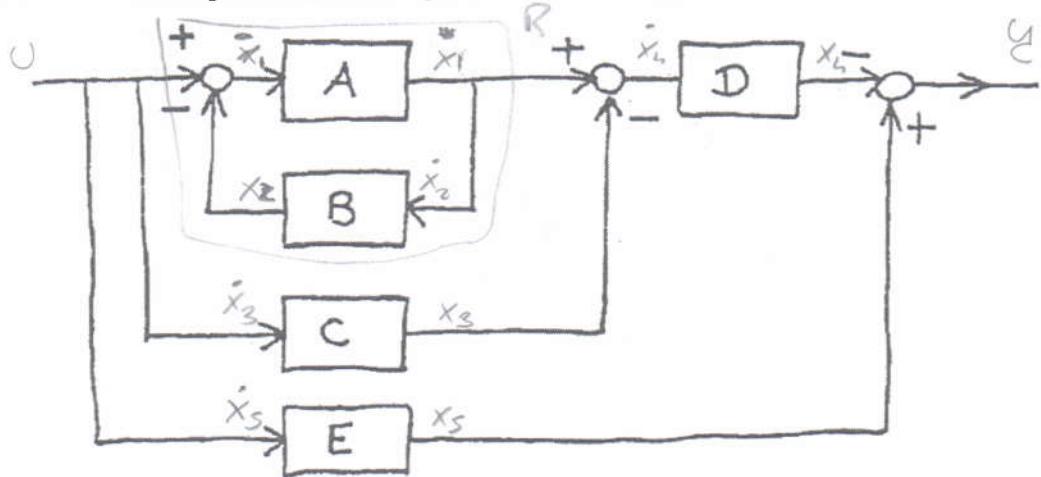


## Esercizio 1

Si consideri il sistema a tempo continuo rappresentato in figura.



Si calcoli la funzione di trasferimento complessiva del sistema.

Supponendo che la funzione di trasferimento di tutti i sistemi sia  $1/s$ , si proponga una possibile realizzazione in spazio di stato del sistema.

①

$$\dot{x}_1 = U - x_2$$

$$\dot{x}_2 = x_1$$

$$\dot{x}_3 = U$$

$$\dot{x}_4 = x_1 - x_3$$

$$\dot{x}_5 = U$$

$$Y = x_5 - x_4$$

$$G(s) = - \left( \frac{A}{1+AB} - C \right) D + E$$

$$= -\frac{1}{s} \left( \frac{1/s}{1+1/s^2} - \frac{1}{s} \right) + \frac{1}{s} = -\frac{1}{s} \left( \frac{s}{s^2+1} - \frac{1}{s} \right) + \frac{1}{s} =$$

$$= \frac{-1}{s^2(s^2+1)} + \frac{1}{s} = \frac{s(s^2+1) + 1}{s^2(s^2+1)}$$

$$s x_1 = U - x_2$$

$$s^2 x_2 = U - x_1 \Rightarrow (s^2 + 1)x_2 = U$$

$$\hookrightarrow sU = U - (x_1 - x_3)$$

$$s^2 U = sU - (U - x_2) + U$$

$$s^2(s^2+1)U = (s(s^2+1) + 1)U$$

**ANNA DI ORDINE  
4. PERCIÙ?**

$$(s^n + d_1 s^{n-1} + \dots + d_n)U = (\beta_1 s^{n-1} + \dots + \beta_n)U$$

**FORMA CANONICA  
DI RICOSTRUZIONE**

$$A_r = \begin{bmatrix} 0 & 0 & \dots & 0 & -d_n \\ 1 & 0 & \dots & 0 & -d_{n-1} \\ 0 & 1 & \dots & 0 & -d_{n-2} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & -\alpha_1 \end{bmatrix}$$

$$B = \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_n \end{bmatrix}$$

$$C^T = \begin{bmatrix} 0 & \dots & 1 \end{bmatrix}$$

$$D = \beta_0$$

$$A_r = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

$$C^T = \begin{bmatrix} 0 & 0 & 0 & 1 \end{bmatrix} \quad D = 0$$

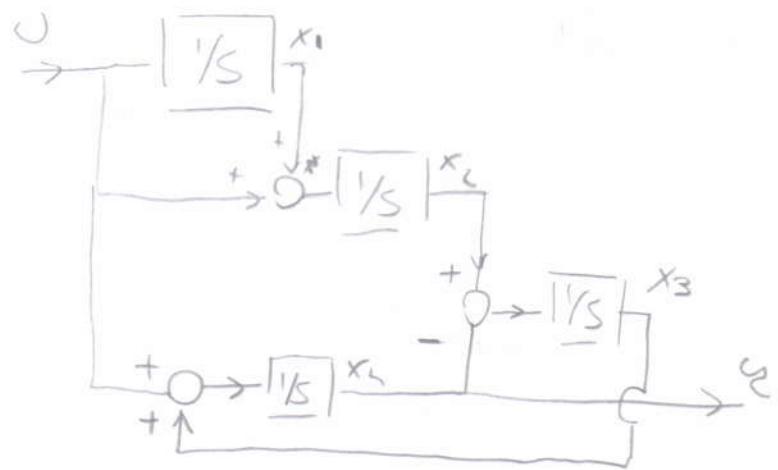
$$\dot{x}_1 = 0$$

$$\dot{x}_2 = x_1 + u$$

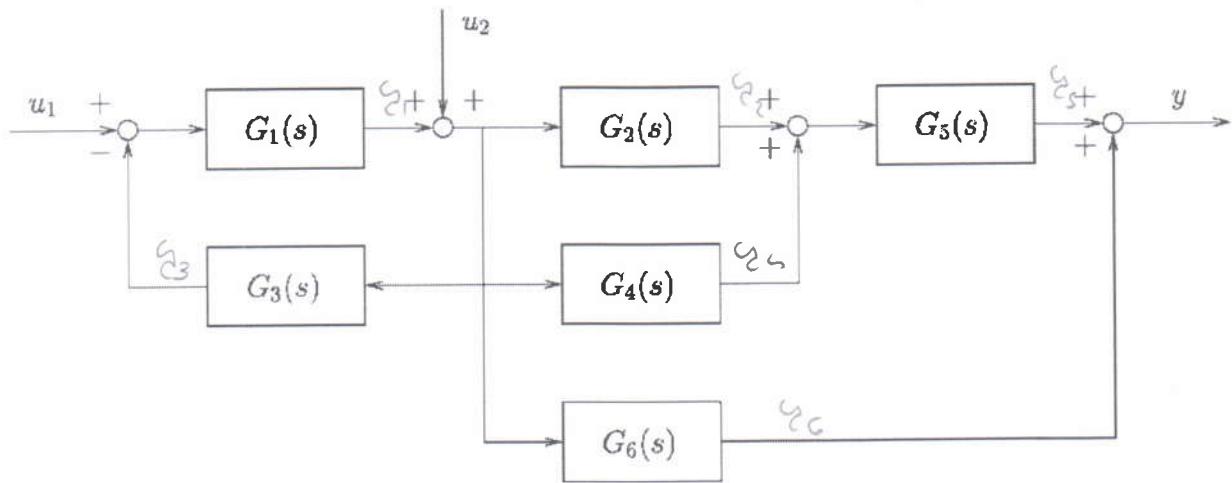
$$\dot{x}_3 = -x_2 - x_4$$

$$\dot{x}_4 = x_3 + u$$

$$y = x_4$$



## Esercizio 2



Si calcoli la funzione di trasferimento complessiva del sistema.

$$U_1 \rightarrow \underline{U} = \frac{G_1}{1+G_1G_3} \left( G_6 + (G_2 + G_4) \underline{G}_5 \right)$$

$$U_2 \rightarrow \underline{U} = \frac{1}{1+G_1G_3} \left( (G_2 + G_4) G_5 + G_6 \right)$$

$$\underline{U} = \underline{U}_5 + \underline{U}_6$$

$$\underline{U}_6 = (U_1 + U_2) G_6$$

$$\underline{U}_5 = (U_2 + \underline{U}_4) G_5$$

$$U_2 + \underline{U}_4 = \frac{G_1}{1+G_1G_3} U_1 + \frac{1+G_1G_3 - G_1G_3}{1+G_1G_3} U_2$$

$$\underline{U}_4 = G_4 (U_2 + \underline{U}_3)$$

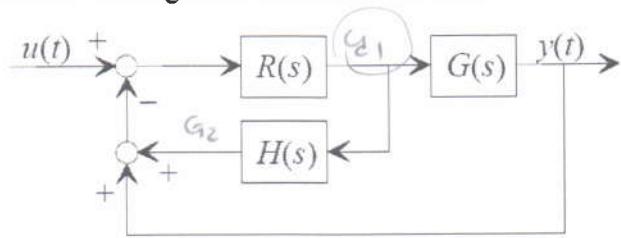
$$\begin{cases} \underline{U}_1 = G_1 (U_1 - \underline{U}_3) \\ \underline{U}_3 = G_3 (U_2 + \underline{U}_1) \end{cases} \Rightarrow \underline{U}_3 = G_3 (U_2 + G_1 (U_1 - \underline{U}_3))$$

$$\underline{U}_3 (1+G_1G_3) = G_3 U_2 + G_1 G_3 U_1$$

$$\underline{U}_1 = \frac{G_1}{1+G_1G_3} ((1+G_1G_3) U_1 - G_3 U_2 - G_1 G_3 U_1)$$

### Esercizio 3

Si consideri il sistema descritto dal seguente schema a blocchi:



$$\text{dove: } R(s) = k, H(s) = \frac{1}{1+5s}, G(s) = \frac{1}{1+10s}$$

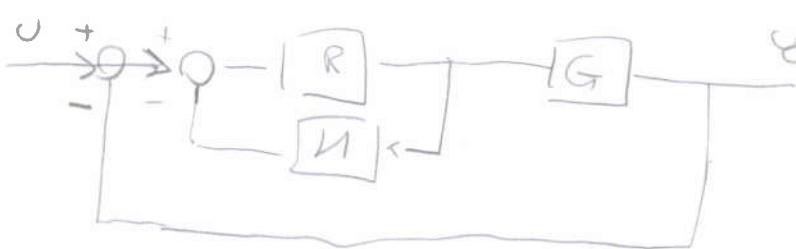
1.1) Determinare la funzione di trasferimento  $F(s)$  tra  $u(t)$  e  $y(t)$ . Commentare il risultato ottenuto

1.2) Determinare per quali valori del parametro  $k$  il sistema è asintoticamente stabile.

1.3) Denotando con  $x_1(t)$  l'uscita del blocco  $G(s)$  e con  $x_2(t)$  l'uscita del blocco  $H(s)$  e ponendo  $k = 1$ , determinare una rappresentazione in forma di stato del sistema.

1.4) Proporre un'altra rappresentazione in forma di stato del sistema

Propongo a ridisegnare.



$$\frac{\frac{RG}{1+RG}}{1 + \frac{RG}{1+nG}} = \frac{RG}{1+RG+nG}$$

$$y = Gx_1$$

$$x_1 = R(u - x_1 - x_2)$$

$$x_2 = Hx_1$$

$$x_1 = R(u - Gx_1 - Hx_1)$$

$$x_1(1 + RG + RH) = RU$$

$$\frac{K}{1+10s} \cdot \frac{1 + \frac{K(1+5s)}{(1+10s)}}{1 + \frac{K(1+5s)}{(1+10s)} + K(2+10s)}$$

$$(1+10s)x_1 = u - x_1 - x_2 \Rightarrow \begin{cases} 10\dot{x}_1 = -2x_1 - x_2 + u \\ 5\dot{x}_2 = -x_1 - 2x_2 + u \end{cases}$$

$$(1+5s)x_2 = u - x_1 - x_2$$

$$y = x_1$$

$$(2+10s)x_1 = u - x_2$$

$$(2+5s)(2+10s)x_1 = (2+5s)u - u + x_1$$

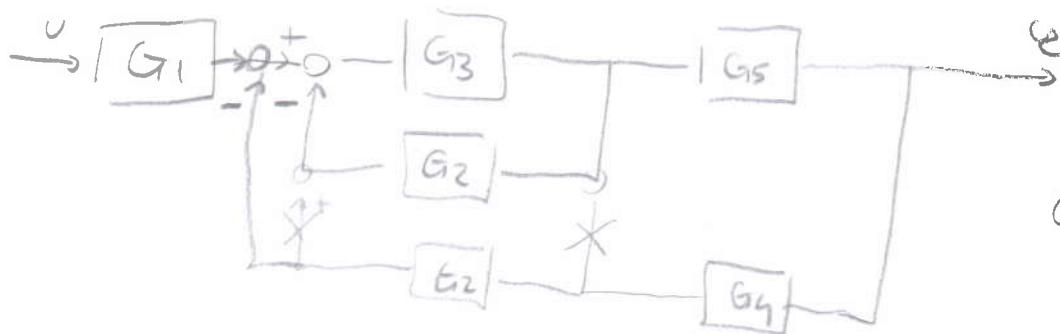
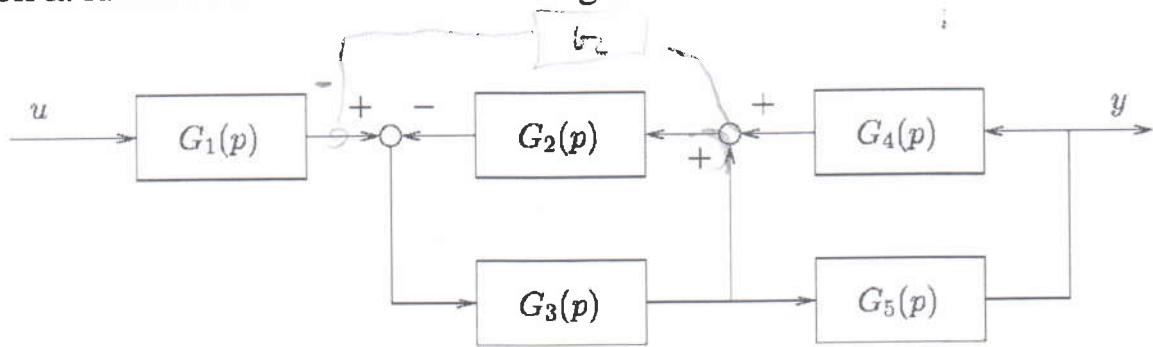
$$(50s^2 + 30s + 3)x_1 = (1+5s)u$$

$$A = \begin{bmatrix} 0 & -3/50 \\ 1 & -3/5 \end{bmatrix} \quad B = \begin{bmatrix} 1/50 \\ 1/10 \end{bmatrix}$$

$$C = \begin{bmatrix} 0 & 1 \end{bmatrix} \quad D = 0$$

### Esercizio 4

Si calcoli la funzione di trasferimento del seguente sistema



$$G_1 \cdot \frac{\frac{G_3 G_5}{1 + G_2 G_3}}{1 + \frac{G_2 G_3 G_4 G_5}{1 + G_2 G_3}} =$$

$$= \frac{G_1 G_3 G_5}{1 + G_2 G_3 + G_2 G_3 G_4 G_5}$$

$$y = G_5$$

$$(1 + G_2 G_3 + G_2 G_3 G_4 G_5) y = G_1 G_3 G_5 \quad \text{①}$$

$$G_5 = G_5 y_3$$

$$y_3 = G_3(y_1 - y_2) \quad - \quad y = G_5 = G_5 \cdot \frac{G_3}{1 + G_2 G_3} (G_1 u - G_2 G_4 y)$$

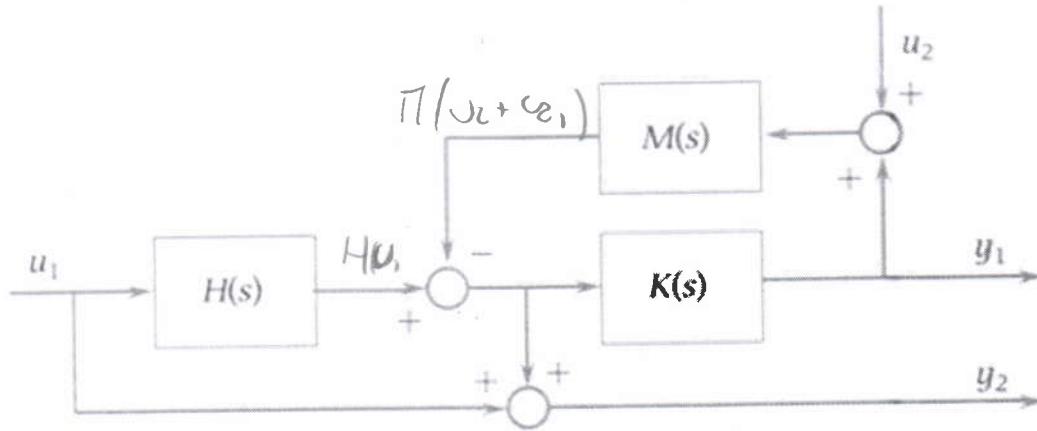
$$y_1 = G_1 u$$

$$y_2 = G_2(y_4 + y_3) \quad - \quad y_3 = G_3(G_1 u - G_2 G_4 y - G_2 y_3)$$

$$y_4 = G_4 y$$

## Esercizio 5

Si calcolino le funzioni di trasferimento del seguente sistema



$$\cdot \quad \dot{e}_1 = K \left( u_1 - \Pi(u_2 + e_1) \right) \Rightarrow \dot{e}_1 = \frac{HK}{1 + \Pi K} u_1 - \frac{\Pi H}{1 + \Pi K} u_2$$

$$\cdot \quad \dot{e}_2 = \dot{e}_1 + Hu_1 - \Pi(u_2 + e_1) = \frac{1 + \Pi K + H + \cancel{HKH} + \cancel{HKH}}{1 + \Pi K} \dot{e}_1 - \frac{\Pi (1 + \cancel{\Pi K} - \cancel{\Pi K})}{1 + \Pi K} u_2$$

